

HI5 2.0 BASIC SDK UNREAL ENGINE

STEAMVR SERIES

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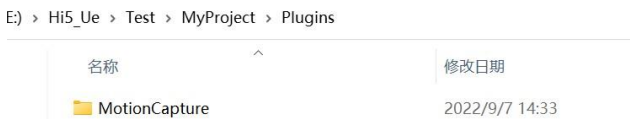
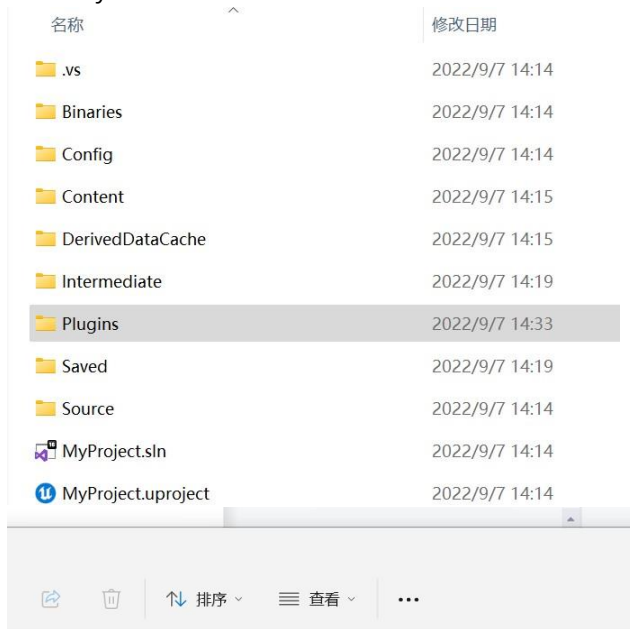
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Create New Project

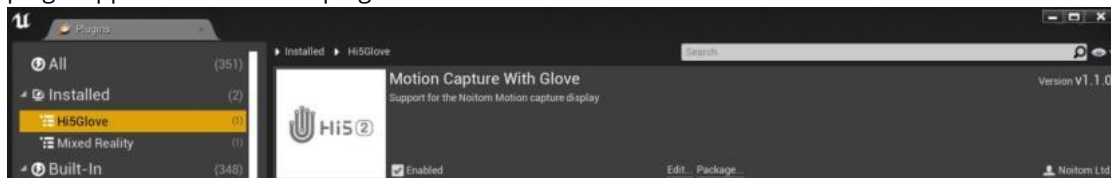
Create new C++ Project

Plugin Import

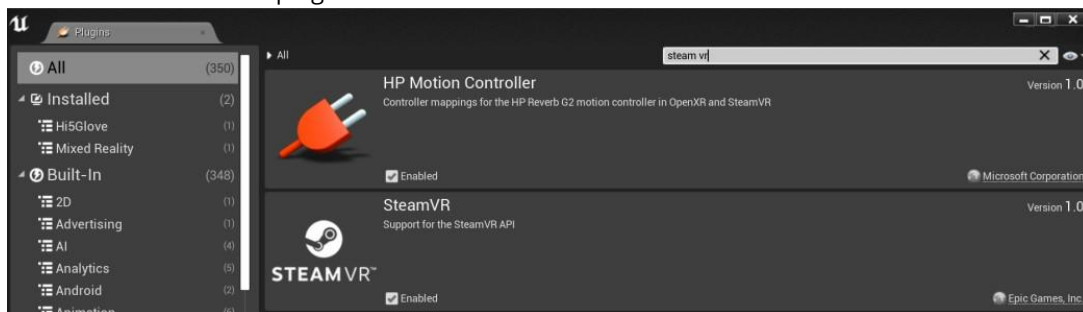
1. Close the project.
2. Open the project folder and create a new Plugins folder. Copy the plugin MotionCapture to the Plugins directory.



3. Reopen the project, click the menu item: Editor -> Plugins, and confirm Motion Capture With Glove. The plugin appears. Activate the plugin and click Restart for it to take effect.



4. Make sure the steam vr plugin is also activated



Add engine Collision settings:

Open the Edit->ProjectSettings->Engine->Collision directory to set

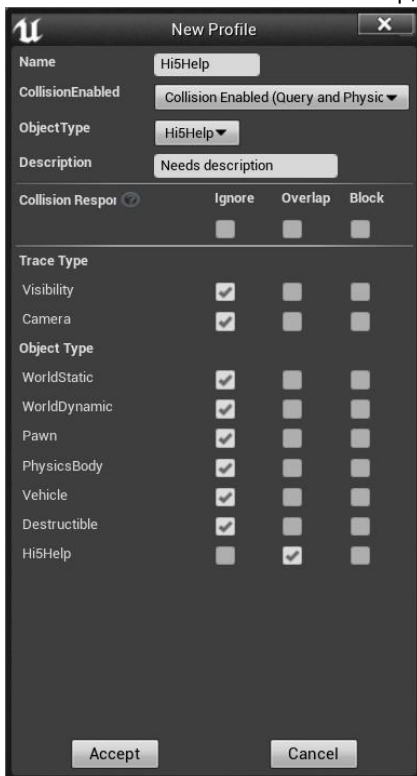
1. Add Object Channels:

Click the New Object Channel button to add Hi5Help, as shown below



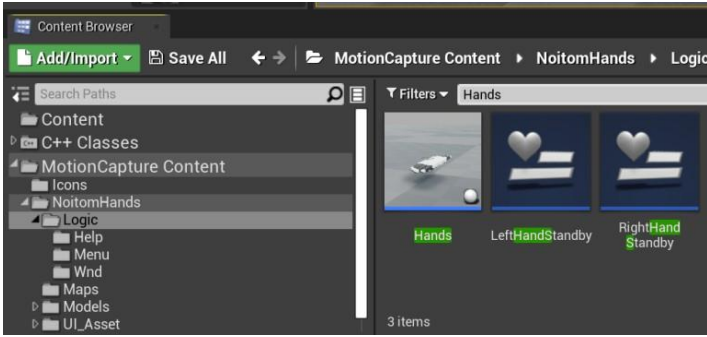
2. Add Preset:

Click the New button to add Hi5Help, as shown below

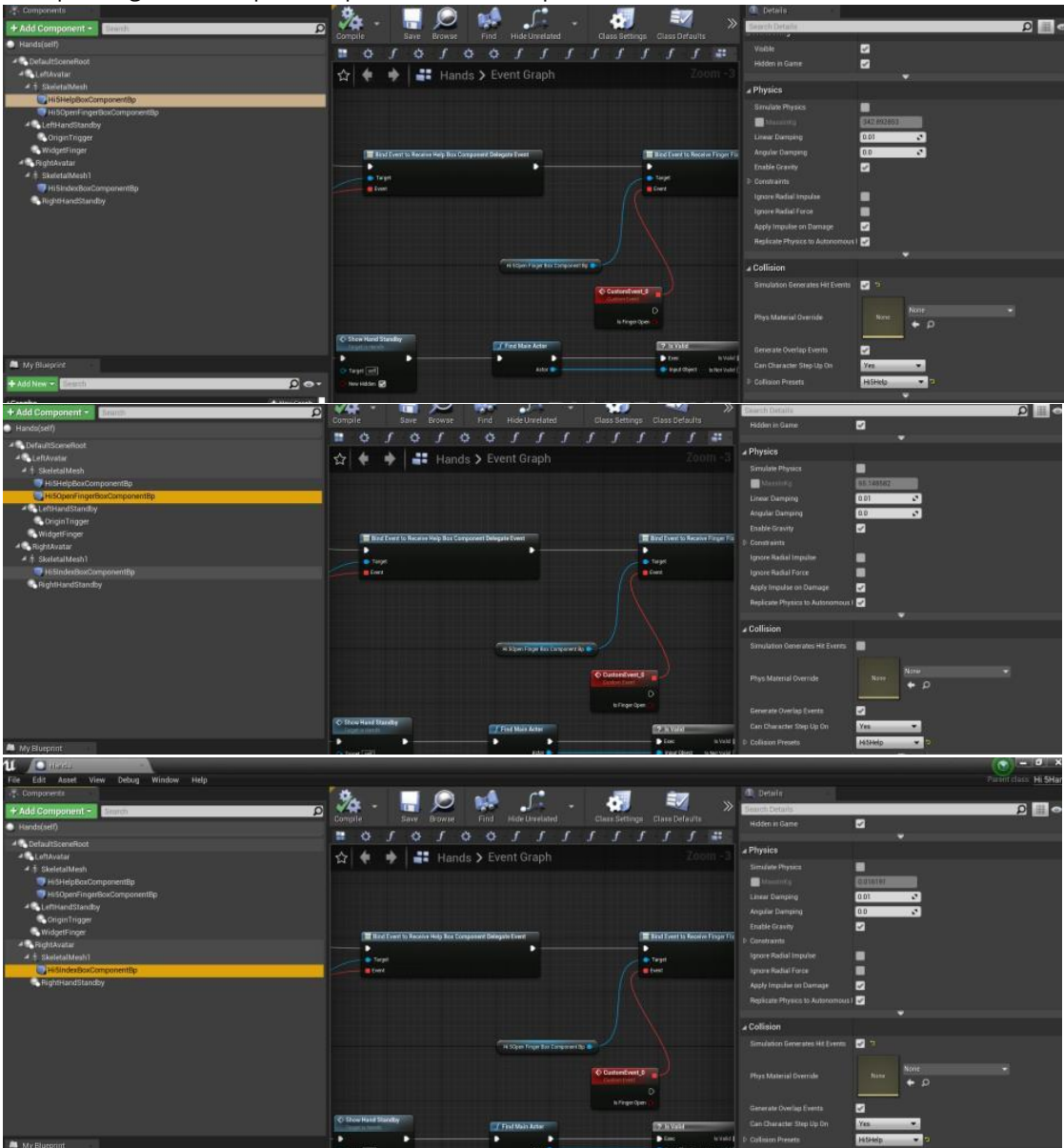


3. Set Hand Collision

Open the Hands blueprint under Content\NoitomHands\Logic



Open Content\NoitomHands\Logic\Help, set Hi5HelpBoxComponentBp, The Collision Presets of the 3 blueprints Hi5IndexBoxComponentBp and Hi5OpenFingerBoxComponentBp are set to Hi5Help.

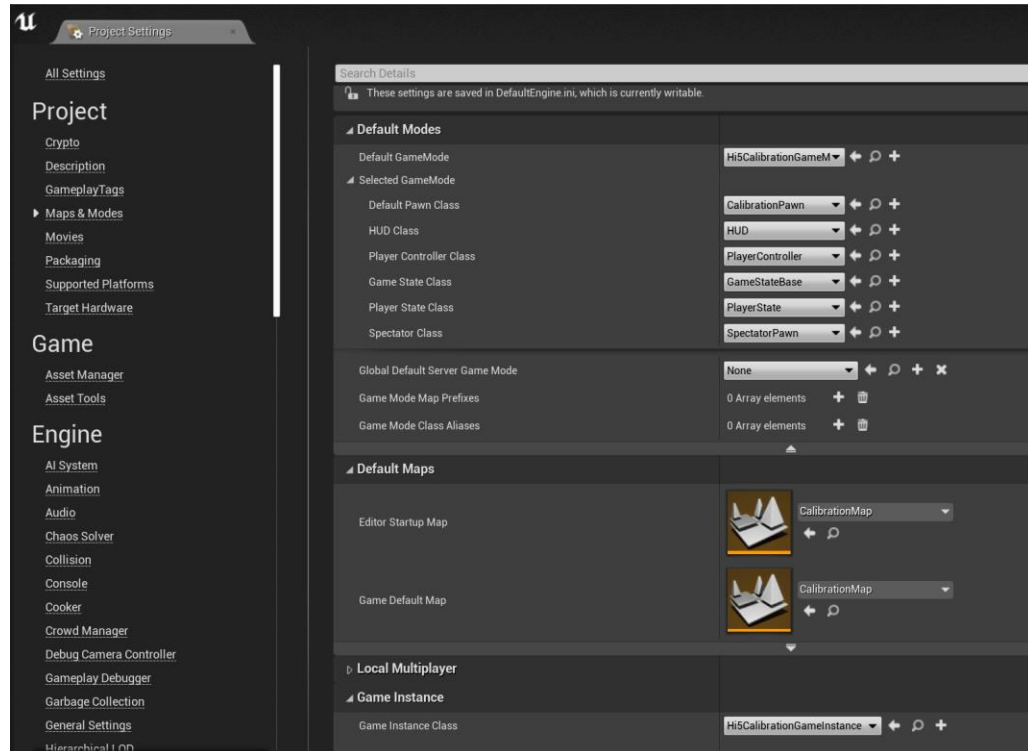


Quickstart

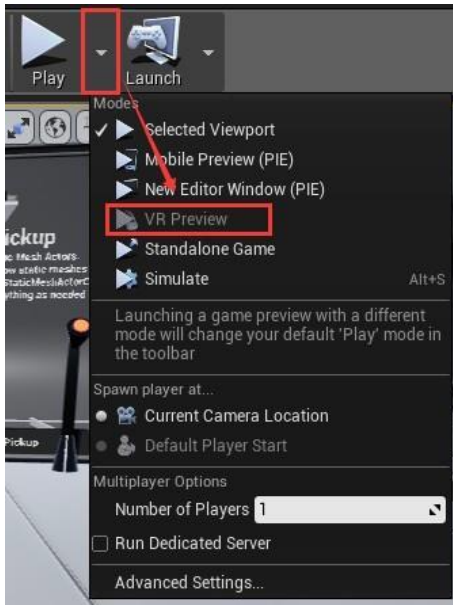
1. Make project settings.

Click the menu items in turn: Editor -> ProjectSettings->Maps&Modes set up:

- Default Modes: Hi5CalibrationGameMode
- Default Pawn Class: CalibrationPawn
- Editor Startup Map: CalibrationMap
- Game Default Map: CalibrationMap
- Game Instance Class: Hi5CalibrationGameInstance



2. Open CalibrationMap under Content\NoitomHands\Maps, compile and save.

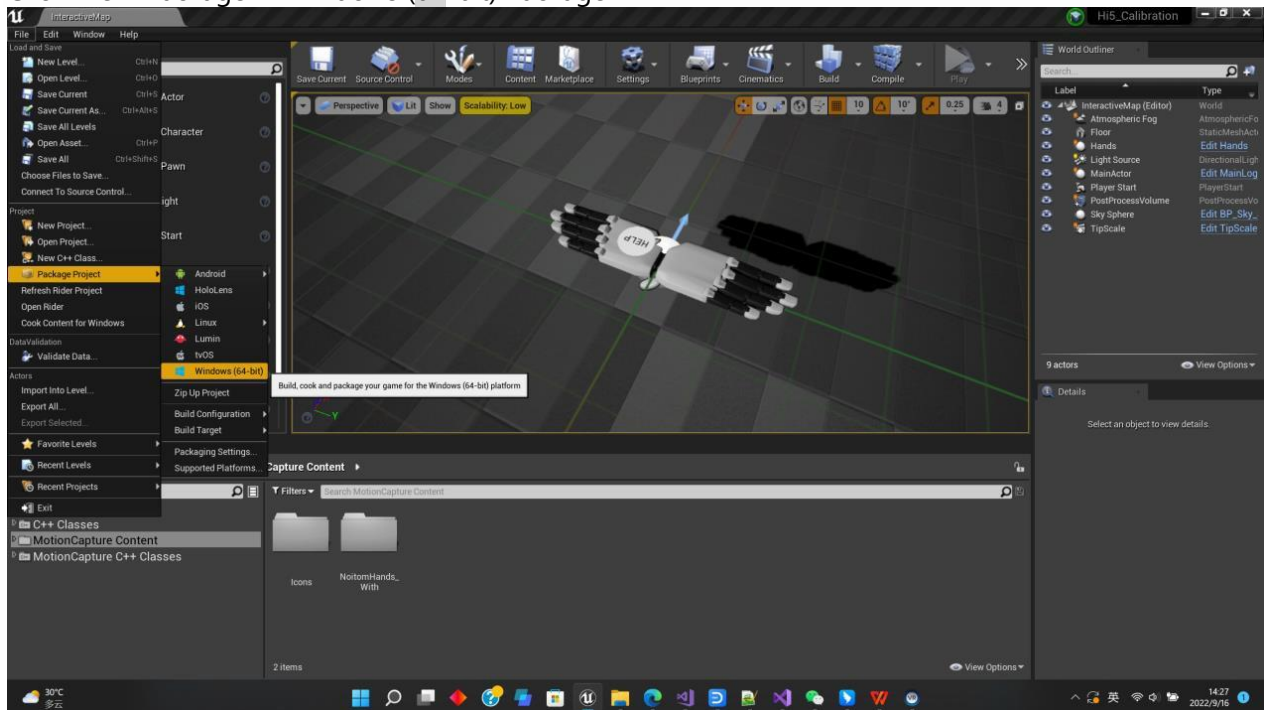


3. After the above steps are completed, you can run the VR Preview mode to use the Hi5_2 Unreal SDK.

*Note: If the VR mode is grayed out and cannot be clicked, please check whether the headset cable is connected correctly and whether the steam vr software can be used normally.

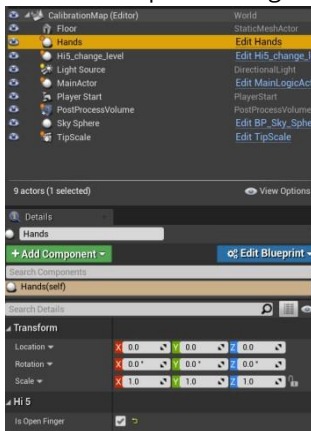
Pack

Click File->Package-> Windows (64-bit) Package

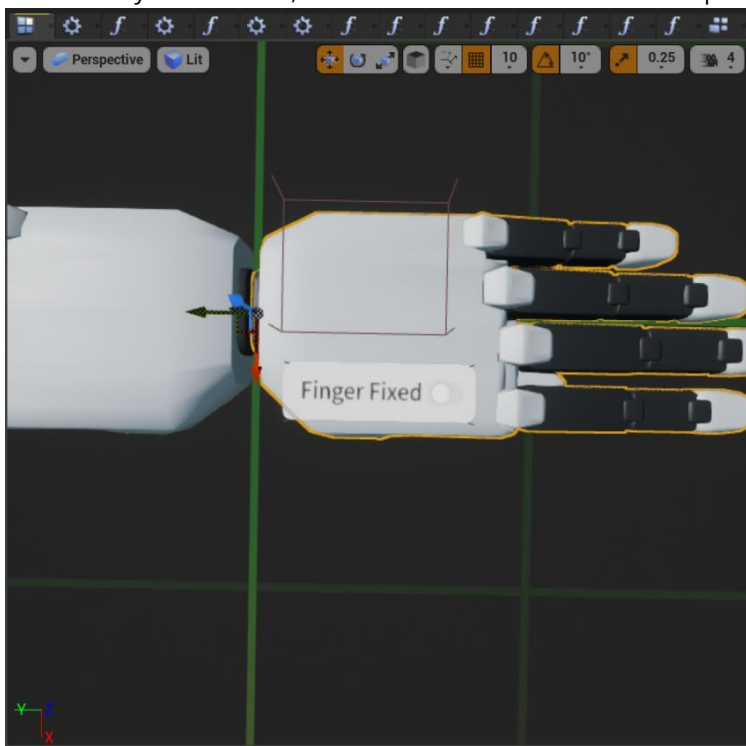


Pointer Function

1. Default setting: Select Hands in World Outliner, and the Is Open Finger option under Hi5 can set whether to open the fingering function.



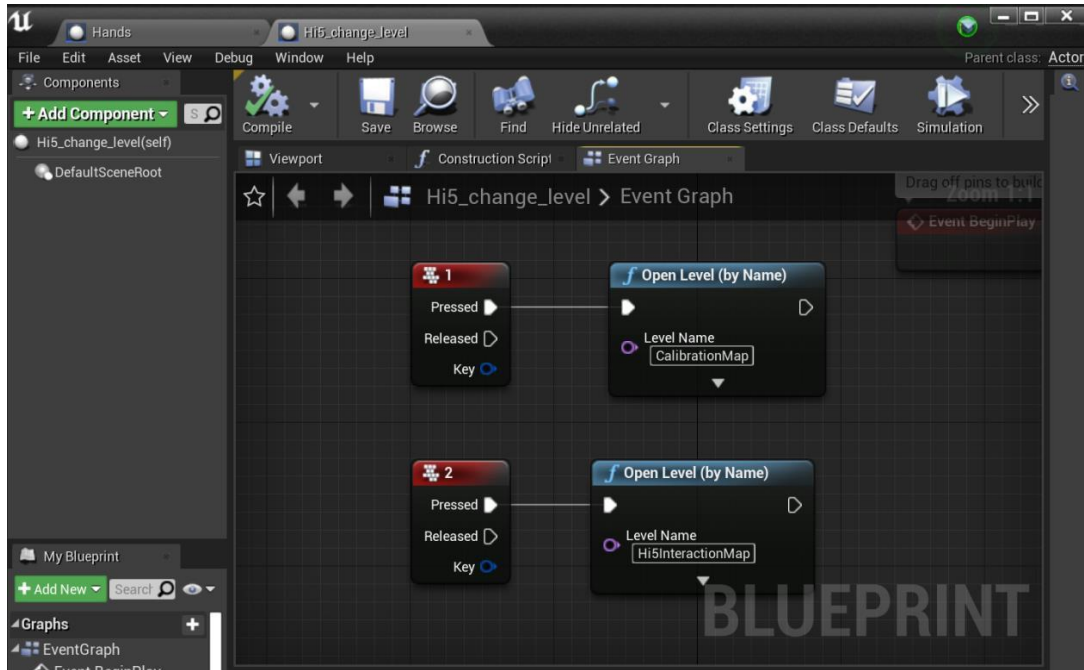
2. Modify during operation: During operation, use your right index finger to click the FingerFixed logo on the back of your left hand, and choose whether to enable the split finger function.



Switch Scenes

Open the Hi5_change_level blueprint under Content\NoitomHands\Logics, and set the Level Name to the Map you want to switch.

Set as shown in the figure below, click keyboard 1 to switch back to the CalibrationMap scene from other scenes.



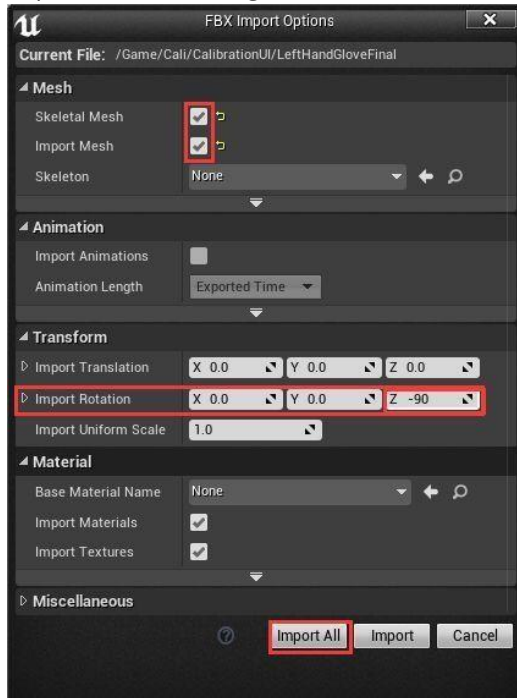
Related asset catalog

MotionCapture\Content\NoitomHands

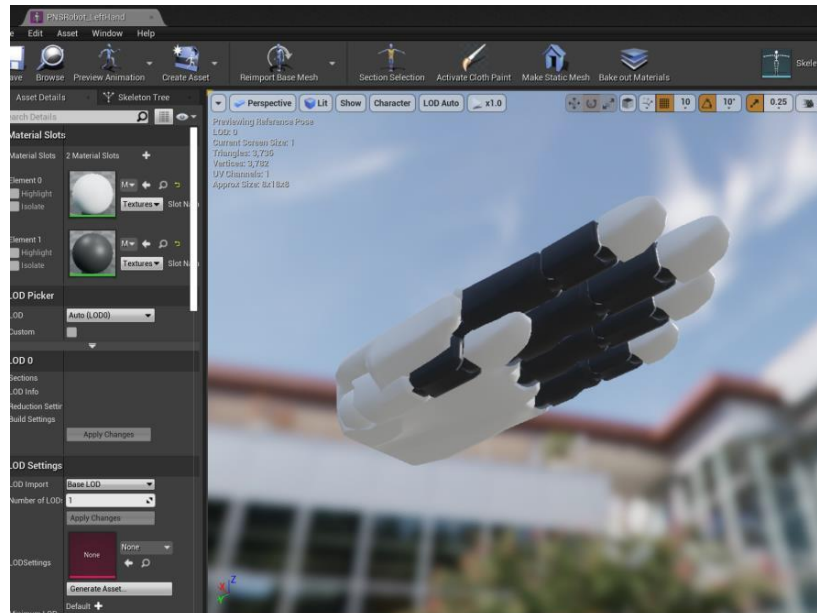
3. Logic folder: Calibration UI interface related blueprints
 - a. CalibrationPawn: Use Pawn for the default calibration, providing related camera Camera and HMD click button function.
 - b. Hands: The Actor contains the hands UMotionCaptureAvatarComponent component, through SkeletalMeshComponent binds hand animation blueprints and meshes.
 - c. MainLogicActor: This Actor integrates the relevant calibration Ui interface and related logic. Contains MainFrameContainer widget (calibration UI interface content display) and MainMenuContainer widget (calibration button panel)
 - d. □ The Menu folder contains subcomponent widgets used by the MainFrameContainer widget
 - e. □ The Wnd folder contains the subcomponent widgets used by the MainMenuContainer widget
4. Map folder
 - a. CalibrationMap: Calibration scene Map
 - b. Hi5CalibrationGameInstance: Hi5 core module startup and exit function
 - c. Hi5CalibrationGameMode: Hi5 related GameMode
5. Models' folder
 - a. The Robothand folder provides related models and animation blueprints used by Hi5.
 - b. The ViveModel folder provides other models used by Hi5.
6. UI_Asset folder
 - a. Associated art textures used by the calibration UI.

Appendix: Hand model import and animation blueprint creation related operations

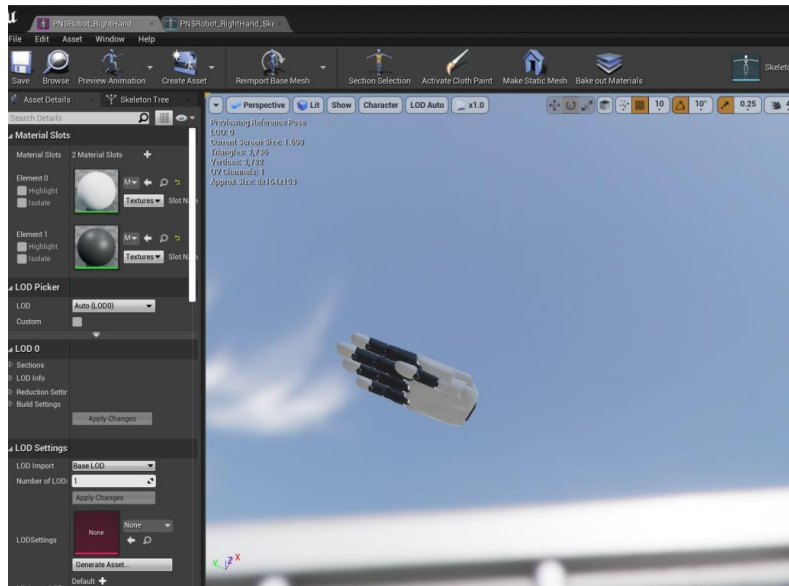
1. Import the left- and right-hand models, the import settings are as follows:



2. The pose of the model after importing is as shown in the figure
 - a. left hand

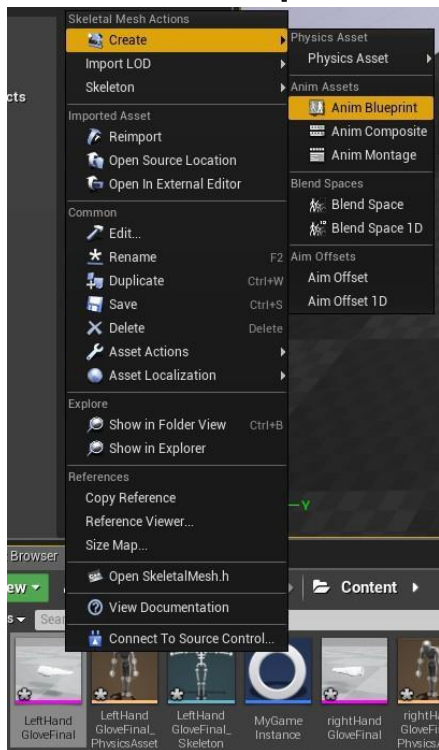


- b. right hand



3. Create animation blueprint

As shown in the figure below, right-click on the left-hand skeletal mesh LeftHandGloveFinal icon, and then select the Create-> [Animation Blueprint] menu item

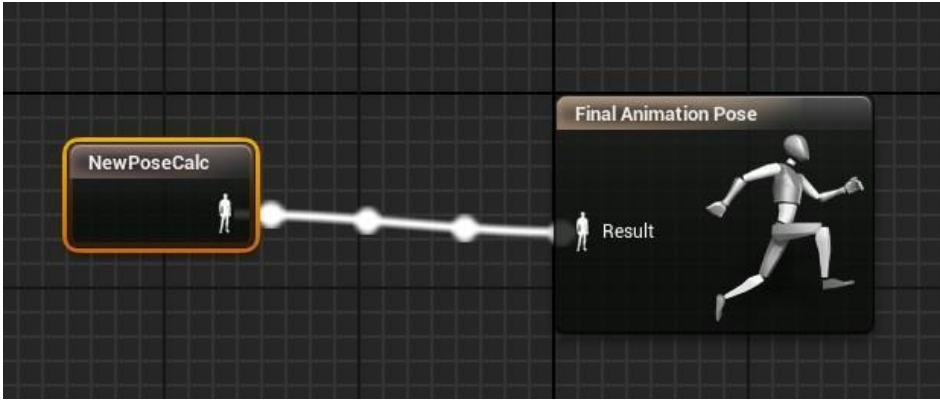


Once complete, we can see the newly created Animation Blueprint in the Content Browser: PNSRobot_LeftHand_Skeleton_AnimBlueprint. The same is true for the right hand, creating animation blueprints.

4. Double-click the newly created Animation Blueprint to open and edit it.

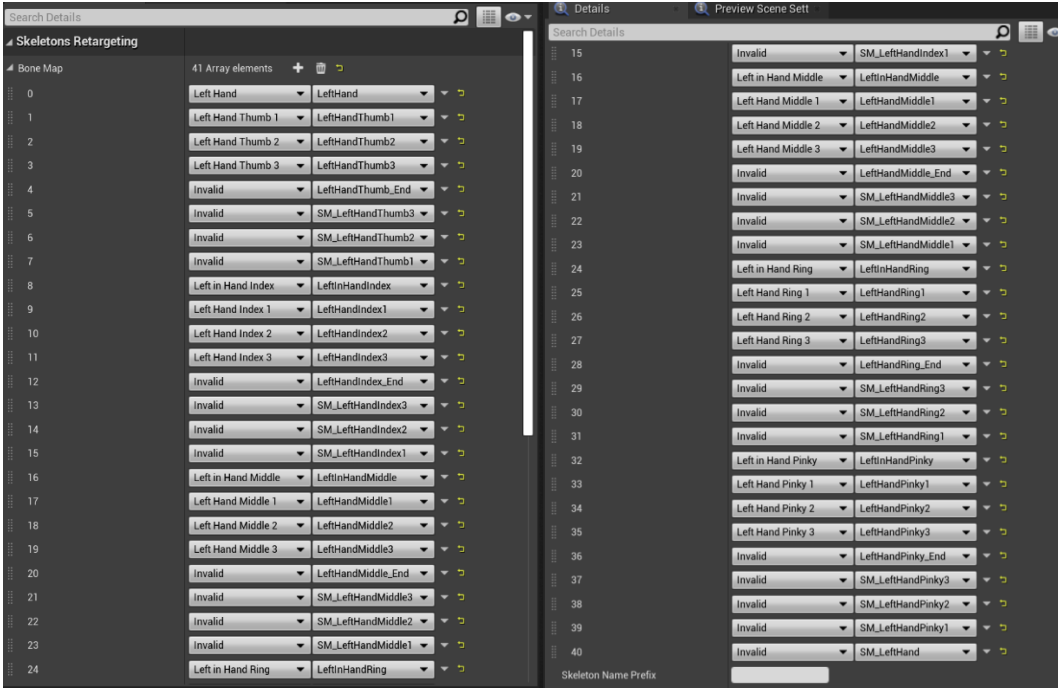
Right-click on the blank space of Anim Graph and create a NewPoseCalc type node, connect NewPoseCalc. The output of the node to the input of the Final Animation Pose node. Compile and save

the Anim Graph when done.

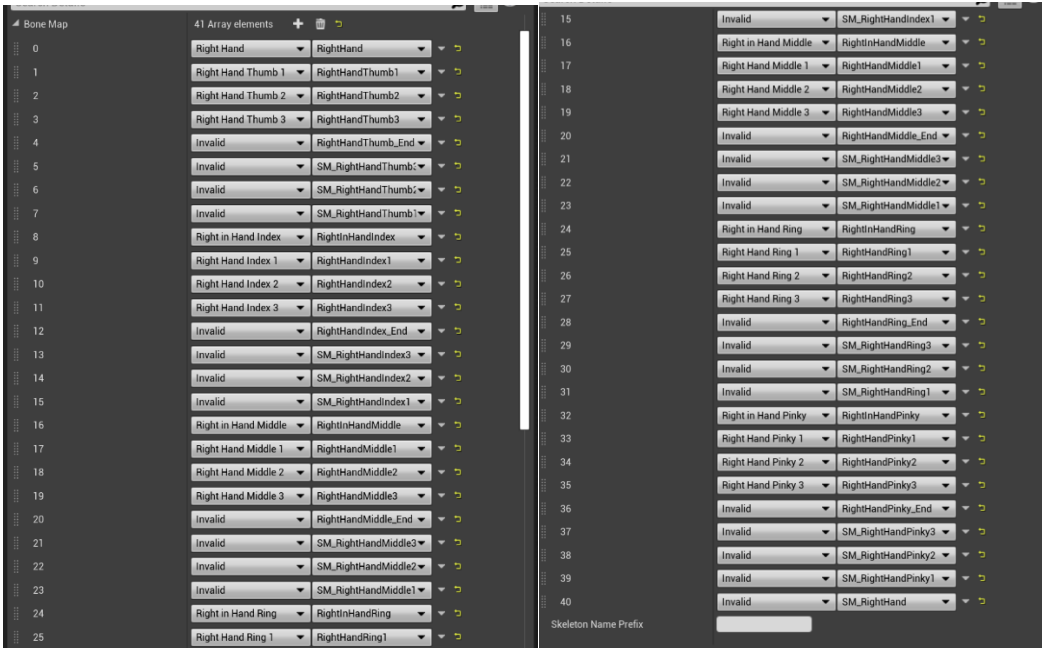


5. Perform bone matching

Select the NewPoseCalc node and expand BoneMap
The left hand is set according to the example picture

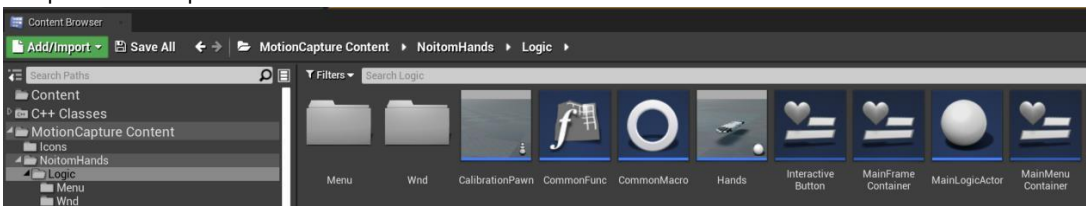


Right hand reference setting

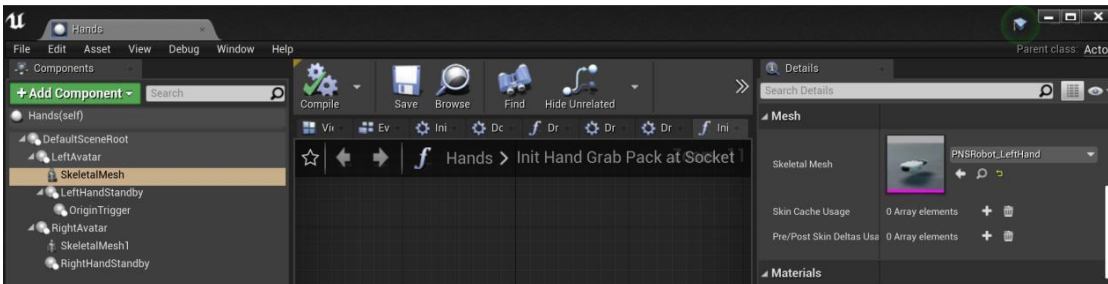


6. Modify the Actor (Hands)

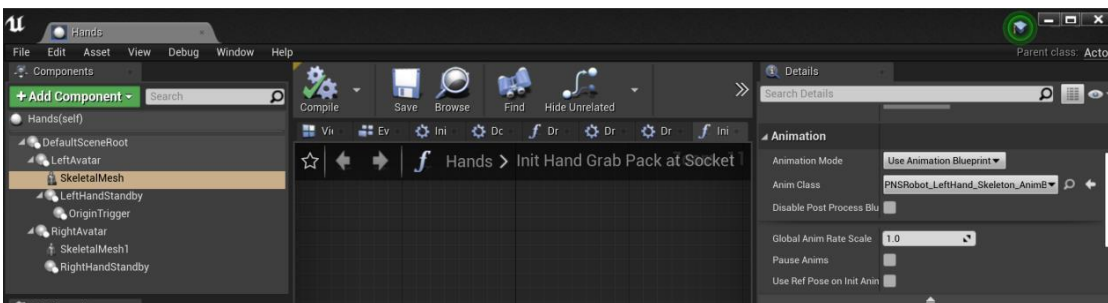
Select Hands (do not copy the new blueprint to use, because there is related blueprint logic in it) click to open the blueprint



Set Mesh



Set Anim classes



The same is true for the right hand.

7. Save and compile after setting.

8. Scene Setup

Drag Hands into the scene and set Transform as follows



Drag the MainActor into the scene

